

We haven't done much so far: just replaced our Steklov problem by another (maybe, slightly easier) problem. Q: What can be said about quasi-eigenvalues τ_m ?

Thm A number $\tau \geq 0$ is a quasi-eigenvalue of a polygon $P_{\vec{\alpha}, \vec{e}}$ iff it is a root of a particular trigonometric fn $F_{\vec{\alpha}, \vec{e}}(\tau)$ next slides

} multiplicity of quasi-ev $\tau > 0$ = mult. of τ as a root of F
 } mult. of q.-e. $\tau = 0$ = $\frac{1}{2}$ (mult. of τ as a root of F)
 (if present)

Constructing trig function $F_{\vec{\alpha}, \vec{\ell}}(\tau)$

$$\mathcal{J}^n := \{\pm 1\}^n$$

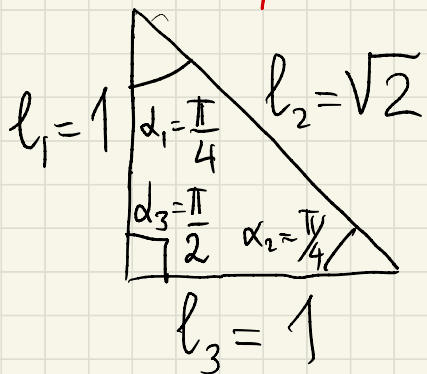
$$F_{\vec{\alpha}, \vec{\ell}} = \sum_{\substack{\vec{\zeta} \in \mathcal{J}^n \\ \zeta_1 = 1}} \rho_{\vec{\zeta}} \cos(\langle \vec{\ell}, \vec{\zeta} \rangle \tau) - \prod_{j=1}^{\infty} \sin \frac{\pi^2}{2\alpha_j}$$

$\text{Ch}(\vec{\zeta}) = \{j \in \{1, \dots, n\} \mid \zeta_j \neq \zeta_{j+1}\}$ set of sign-changes in $\vec{\zeta}$

e.g. $\text{Ch}((1, 1, 1)) = \emptyset$, $\text{Ch}((-1, -1, 1, 1)) = \{2, 4\}$

$$\rho_{\vec{\zeta}} := \prod_{j \in \text{Ch}(\vec{\zeta})} \cos \frac{\pi^2}{2\alpha_j}$$

Example



| \vec{s} | $\langle \vec{l}, \vec{s} \rangle$ | $\text{Ch}(\zeta)$ | $\mathcal{P}_{\vec{s}}$ |
|-------------|------------------------------------|--------------------|-------------------------|
| $(+, +, +)$ | $2 + \sqrt{2}$ | \emptyset | 1 |
| $(+, +, -)$ | $\sqrt{2}$ | $\{2, 3\}$ | -1 |
| $(+, -, +)$ | $2 - \sqrt{2}$ | $\{1, 2\}$ | 1 |
| $(+, -, -)$ | $-\sqrt{2}$ | $\{1, 3\}$ | -1 |

Also $\prod_{j=1}^3 \sin \frac{\pi^2}{2\alpha_j} = 0$

Thus $F_{\vec{x}, \vec{l}}(\tau) = \cos((2 + \sqrt{2})\tau) - 2\cos(\sqrt{2}\tau) + \cos((2 - \sqrt{2})\tau)$

$= -4(\cos^2 \tau - 1)\cos(\sqrt{2}\tau) \Rightarrow$ we have

- a single q.e. at $\tau = 0$
- double q.e's at $\tau = \pi m, m \in \mathbb{N}$
- single q.e's at $\tau = \frac{\pi}{\sqrt{2}} \left(m - \frac{1}{2} \right)$, $m \in \mathbb{N}$

More can be said about the asymptotics of Steklov eigenvalues and eigenfunctions

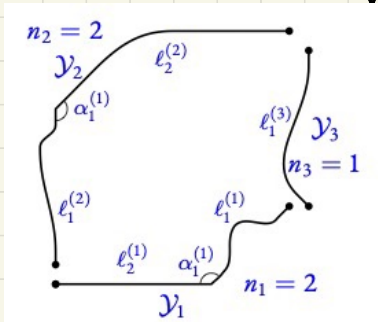
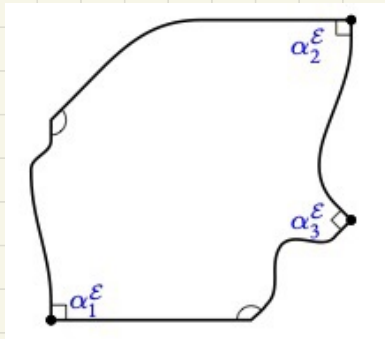
- As we will see, a particular role is played by some arithmetic properties of the angles, specifically by the presence or absence of the **exceptional angles** from the set $\mathcal{E} := \left\{ \frac{\pi}{2k}, k \in \mathbb{N} \right\}$

- We'll also mention **special angles**

$$\mathcal{S} := \left\{ \frac{\pi}{2k-1}, k \in \mathbb{N} \right\}$$

- In either case $\alpha \in \mathcal{E} \cup \mathcal{S}$, the oddity of the angle is defined as $\mathcal{O}(\alpha) = (-1)^k$.

In the presence of exceptional angles $\alpha_1^\varepsilon, \dots, \alpha_K^\varepsilon$:
 we need some re-labelling



- they split the boundary into K exceptional boundary components

$\gamma_{\mathcal{R}}$, each with $n_{\mathcal{R}}$

pieces, $\mathcal{R} = 1, \dots, K$, so

$$n_1 + \dots + n_K = n$$

$$\vec{l}^{(\mathcal{R})} = (l_1^{(\mathcal{R})}, \dots, l_{n_{\mathcal{R}}}^{(\mathcal{R})})$$

- \mathcal{R} th component has lengths and angles $\vec{\alpha}^{(\mathcal{R})} = (\alpha_1^{(\mathcal{R})}, \dots, \alpha_{n-1}^{(\mathcal{R})})$

- An exc. boundary component may be $\begin{cases} \text{even, } \sigma(\alpha_{\mathcal{R}}^\varepsilon) = \sigma(\alpha_{\mathcal{R}-1}^\varepsilon) \\ \text{odd, } \sigma(\alpha_{\mathcal{R}}^\varepsilon) \neq \sigma(\alpha_{\mathcal{R}-1}^\varepsilon) \end{cases}$

Non-exceptional case vs Exceptional case

$\sigma = 0$ | present only if $\prod_{j=1}^n \tan \frac{\pi^2}{4\alpha}$
 $= 1$; always simple

has multiplicity $\frac{1}{2} K_{\text{odd}}$
 # of odd except. bdy comps

$\sigma > 0$ | multiplicity one or two

any multiplicity up to K

$F(\tau)$

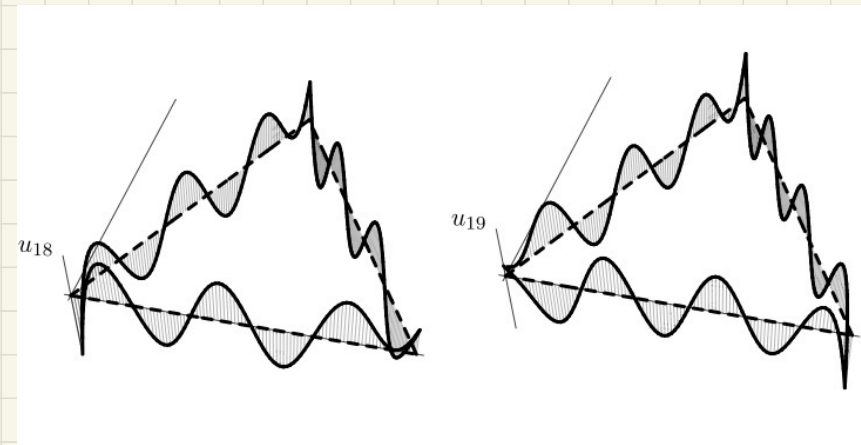
factorises: $F_{\vec{a}, \vec{b}}(\tau) = \prod_{\mathcal{R}=1}^K F_{\text{even/odd}, \mathcal{R}}(\tau)$

eigen-functions of \mathcal{D}_0 | "equidistributed" over the whole boundary

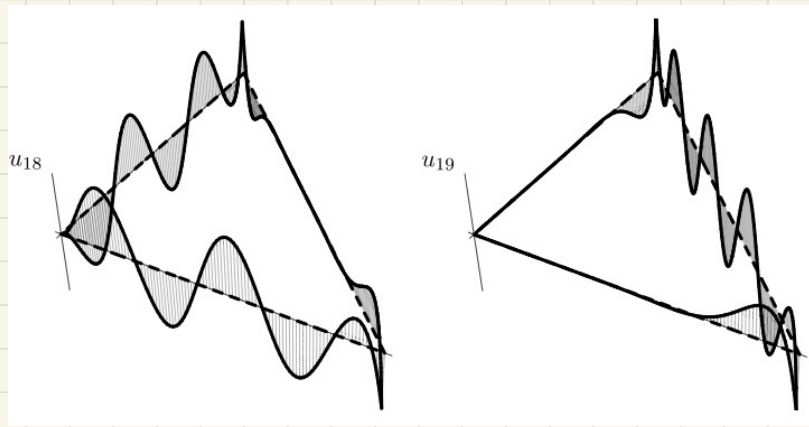
concentrate on some exceptional bound. components

In the last line equidistributed means that for any arc $I \subset \partial \mathcal{D}$ (does not have to be a side)

$$\lim_{m \rightarrow \infty} \frac{\|U_m\|_{L^2(I)}}{\|U_m\|_{L^2(\partial \mathcal{D})}} = \frac{|I|}{|\partial \mathcal{D}|}$$



non-exceptional case,
equilateral Δ -gle



exceptional case,
 $90^\circ - 45^\circ - 45^\circ$ Δ -gle

MAIN STEPS OF THE PROOFS

- The result about $F_{\vec{q}, \vec{\ell}}(\tau)$ is obtained by just writing out the secular equation of our quantum graph $M_{\vec{q}, \vec{\ell}}$: requires some trickery, but generally straight-forward
- The difficult part is about quasi-eigenvalues, and we first need another classical hydrodynamics problem...

The sloping beach problems in an infinite sector

$$\partial\Phi/\partial y = \Phi$$

$$\Delta\Phi = 0$$

$$\partial\Phi/\partial n = 0$$

$$\partial\Phi/\partial n = 0$$

$$\Phi = 0$$

on

Question:

are there solutions
bounded in $\overline{G}_{\alpha/2}$
and such that

$$\Phi(x, y) = \cos\left(x - \frac{\pi}{3}\right) e^y + R(x, y)$$

with

$$\rho = \sqrt{x^2 + y^2}$$

$$R(x, y) + |\rho \nabla R(x, y)| = O(\rho^{-\tau}),$$

with some $\tau > 0$ $\rho \rightarrow \infty$

Answers: **yes** if one takes particular values
of constant

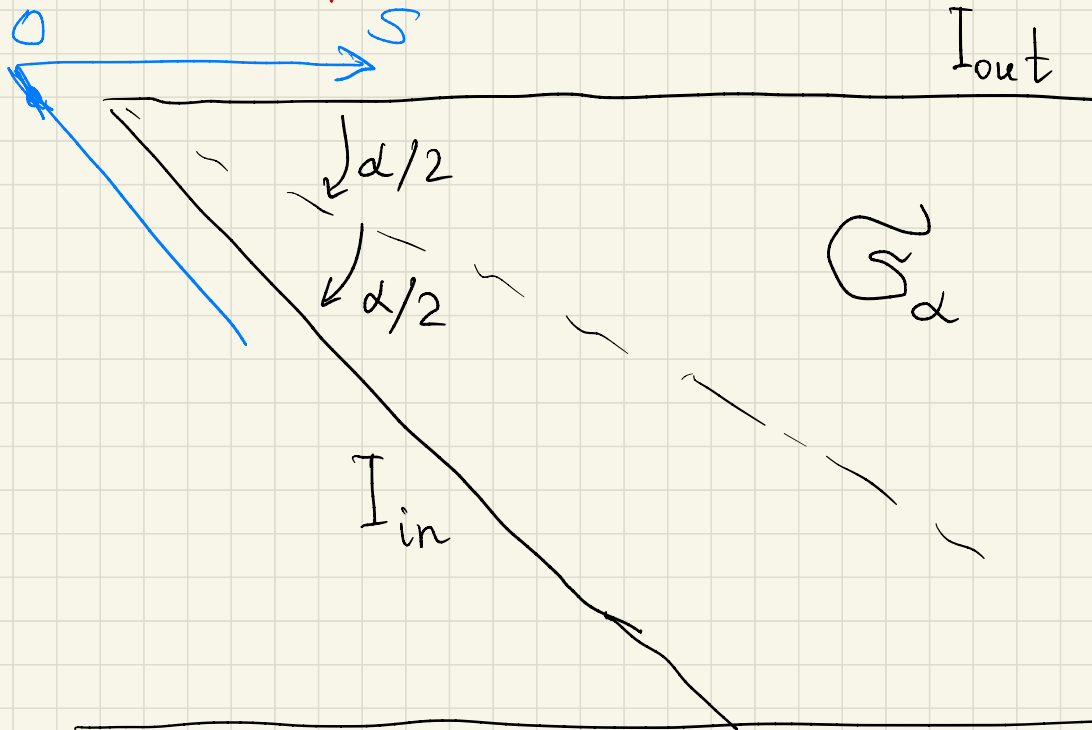
$$\underline{c_{nr}} = \begin{cases} \underline{c}_{\alpha/2, \text{Neu}} = \frac{\pi}{4} - \frac{\pi^2}{4\alpha} & \text{for Neu on the bottom} \\ \underline{c}_{\alpha/2, \text{Dir}} = \frac{\pi}{4} + \frac{\pi^2}{4\alpha} & \text{for Dir on the bottom} \end{cases}$$

[originally due to Lewy and Peters 40s-50s,
improved/extended by us; we can take $\Gamma = \frac{\pi}{\alpha}$
in the remainder]

We will denote the corresponding solutions

$$\Phi_{\alpha/2, \text{Neu}}(x, y) \text{ and } \Phi_{\alpha/2, \text{Dir}}(x, y)$$

Robin problem in the "full" sector \mathbb{S}_α



$$\begin{cases} \Delta \tilde{\Phi} = 0 & \text{in } \mathbb{S}_\alpha \\ \partial_n \tilde{\Phi} = \tau \tilde{\Phi} & \text{on } I_{in} \cup I_{out} \end{cases}$$

τ large

$\Phi_{\text{symm}}(x, y)$ - symmetric extension of $\Phi_{\alpha/2, \text{New}}(\tau x, \tau y)$
 $\Phi_{\text{antis.}}(x, y)$ - antisymm. extension of $\Phi_{\alpha/2, \text{Dir}}(\tau x, \tau y)$

Consider now a non-trivial linear comb. of Φ_{symm} , Φ_{antisym}
It solves the Robin problem in the full sector.

Moreover, its traces on the boundary rays $I_{\text{in/out}}$
behave as

$$\tilde{\Phi}|_{I_{\text{in}}}(s) = h_{\text{in},1} e^{its} + h_{\text{in},2} e^{-its} + o(1) \quad (*)$$

$$\tilde{\Phi}|_{I_{\text{out}}}(s) = h_{\text{out},1} e^{its} + h_{\text{out},2} e^{-its} + o(1)$$

with some vectors $\vec{h}_{\text{in/out}} = \begin{pmatrix} h_{\text{in/out},1} \\ h_{\text{in/out},2} \end{pmatrix} \in \mathbb{C}^2$

We call such a solution $\tilde{\Phi}_\tau(x, y; \vec{h}_{\text{in}}, \vec{h}_{\text{out}})$
a Peters solution

Next question: what should be the relations (if any) between the vectors \vec{h}_{in} , \vec{h}_{out} for a Peters soln with given asymptotics to exist?

Some linear algebra + trigonometry gives

Thm • let $\alpha \notin \mathbb{Z}$. Then for every $\vec{h}_{in} \in \mathbb{C}^2$ there exists a Peters soln $\tilde{\Phi}_\alpha(x, y; \vec{h}_{in}, \vec{h}_{out})$ if

we take $\vec{h}_{out} = \underbrace{\begin{pmatrix} \operatorname{cosec} \frac{\pi^2}{4\alpha} & -i \cot \frac{\pi^2}{4\alpha} \\ i \cot \frac{\pi^2}{4\alpha} & \operatorname{cosec} \frac{\pi^2}{4\alpha} \end{pmatrix}}_{A(\alpha)} \vec{h}_{in}$

$$A(\alpha)$$

contd...

• let $\alpha = \frac{\pi}{2k} \in \mathcal{E}$, $k \in \mathbb{N}$. Then a Peters soln exists if the vectors $\vec{h}_{in}, \vec{h}_{out}$ satisfy

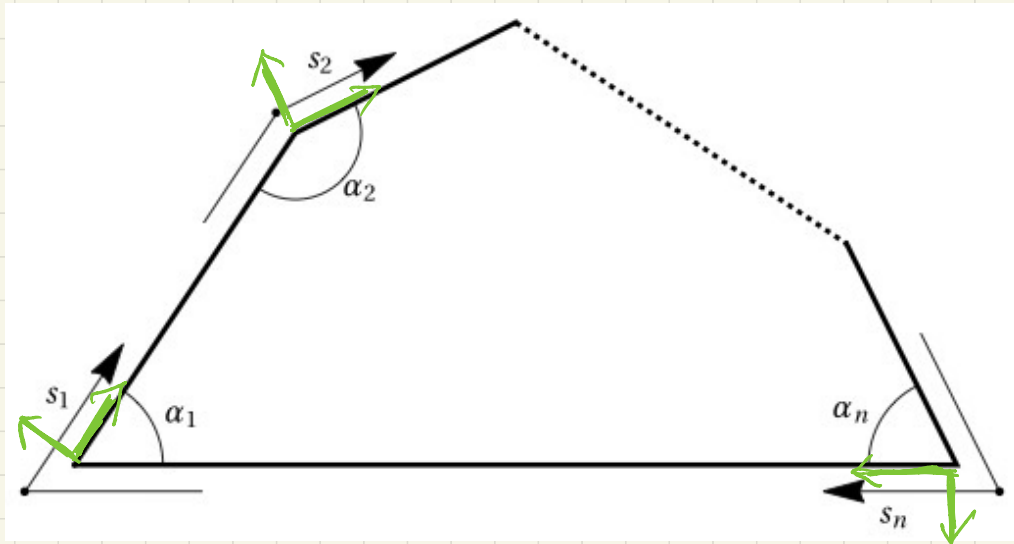
$$\langle \vec{h}_{in}, \vec{X} \rangle_{\mathbb{C}^2} = \langle \vec{h}_{out}, \vec{X} \rangle_{\mathbb{C}^2} = 0, \text{ where}$$

$$\vec{X} = \begin{pmatrix} e^{(-1)^{k+1} i\pi/4} \\ e^{(-1)^k i\pi/4} \end{pmatrix}$$

Remarks: • in both cases we choose two of the four quantities $\vec{h}_{in}, \vec{h}_{out} \in \mathbb{C}^2$ but do this differently

• $A(\alpha)$ invertible $\iff \alpha \notin \mathcal{E}$.

Constructing the quasimodes for a straight polygon: an outline



local boundary
coordinate s_n
centred at V_n

V_j : sector $V_{j-1} V_j V_{j+1} \mapsto$ sector \mathbb{G}_{α_j}
 $\underline{(x'_j, y'_j)} = V_j(x, y)$ local Cart. coordinates

We seek **quasimodes** of the Steklov problem

$\tilde{U}_\tau(x, y)$ such that near each vertex

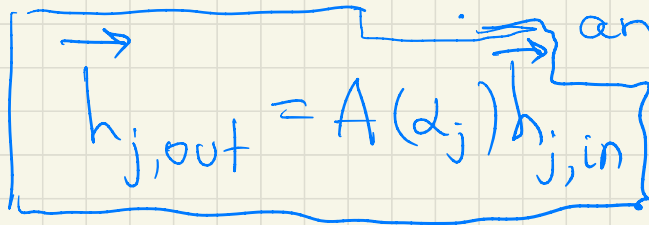
$$\tilde{U}_\tau(x, y) = \tilde{\Phi}_\tau(x'_j, y'_j; \vec{h}_{j, \text{in}}, \vec{h}_{j, \text{out}})$$

with **still unknown**
vectors $\vec{h}_{j, \text{in}}, \vec{h}_{j, \text{out}}$

← a Peters solution

For simplicity, assume there are no exceptional angles

Then we must have


$$h_{j, \text{out}} = A(\alpha_j) h_{j, \text{in}}$$

We also have $\tilde{U}_\tau|_{\partial\mathcal{D}} = \tilde{u} + o(1)$ $\tau \rightarrow \infty$

Consider $\tilde{u}|_{I_j}$. It may be written in two ways:
side joining V_{j-1} and V_j

a trigonometric fn in S_j involving vectors $\vec{h}_{j,in}, \vec{h}_{j,out}$

(using Peters soln near V_j)

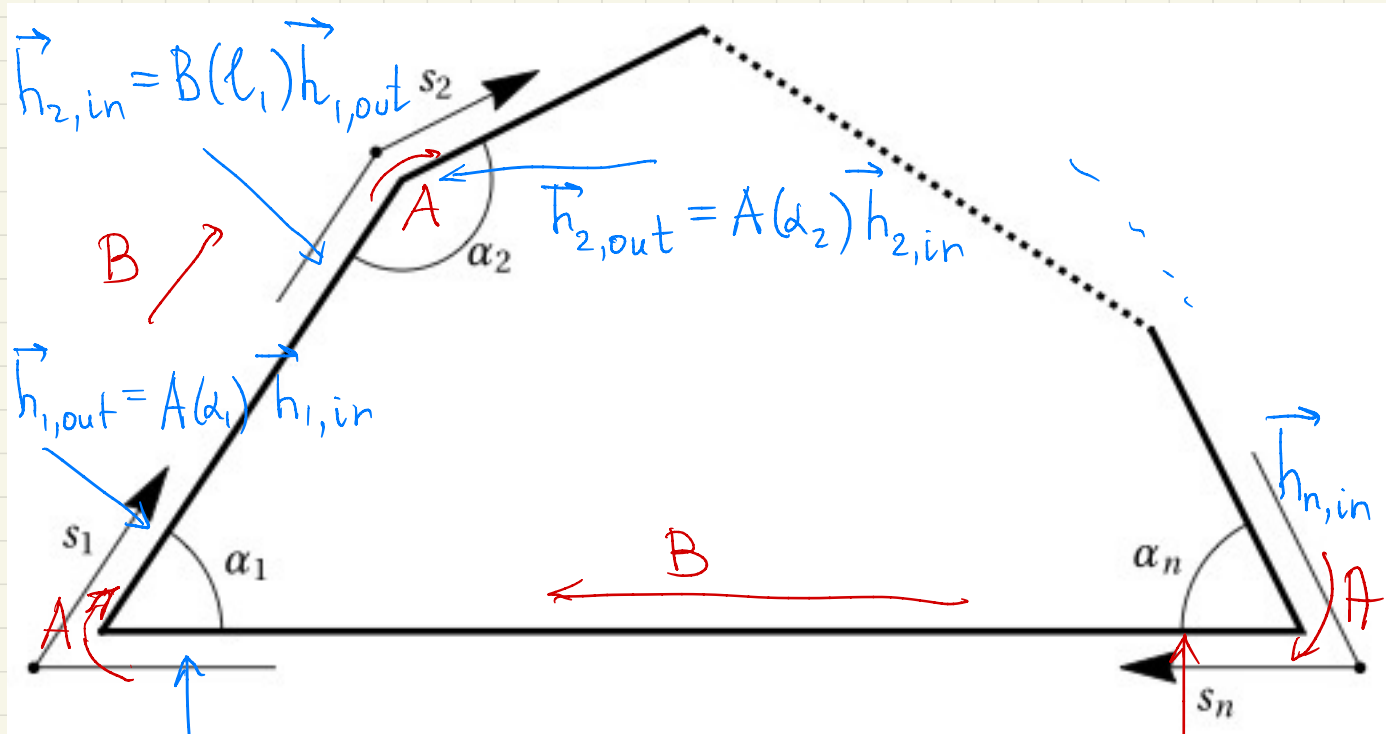
= a trig. fn in S_{j-1} using vectors $\vec{h}_{j-1,in}, \vec{h}_{j-1,out}$

(using Peters soln near V_{j-1})

A calculation gives $\vec{h}_{j,in} = B(l_j, \tau) \vec{h}_{j-1,out}$

where $B(l, \tau) := \begin{pmatrix} e^{i l \tau} & 0 \\ 0 & e^{-i l \tau} \end{pmatrix}$

So, what do we get?



$$\vec{h}_{2,in} = B(d_1) \vec{h}_{1,out}$$

$$\vec{h}_{2,out} = A(d_2) \vec{h}_{2,in}$$

$$\vec{h}_{1,out} = A(d_1) \vec{h}_{1,in}$$

$$\vec{h}_{1,in} = B(d_n) \vec{h}_{n,out}$$

Start here
 $\vec{h}_{n,out}$

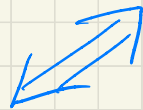
Thus, we've arrived at the equation

$$\vec{h}_{n,\text{out}} = A(\alpha_n) B(\ell_n, \tau) A(\alpha_{n-1}) B(\ell_{n-1}, \tau) \cdots A(\alpha_1) B(\ell_1, \tau) \vec{h}_{n,\text{out}}$$

$$:= T(\vec{\alpha}, \vec{\ell})$$

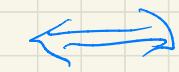
product of $2n$ 2×2 matrices

Therefore the matrix $T(\vec{\alpha}, \vec{\ell})$ has an eigenvalue 1



(easy check)

$$\text{Tr}(T(\vec{\alpha}, \vec{\ell})) = 2$$



(difficult
check)

$$F_{\vec{\alpha}, \vec{\ell}}(\tau) = 0$$

What remains to be done?

- Rigorous construction of the quasimodes \tilde{U}_{τ_m} using appropriate cut-offs
- Then it is relatively easy to see that

$$\|\partial_n \tilde{U}_{\tau_m} - \tau_m \tilde{V}_{\tau_m}\|_{L^2(\partial\Omega)} \rightarrow 0$$

so they are indeed quasimodes: ↑ quantitatively

there exists a subsequence of exact Steklov e.v.'s δ_{i_m} s.t.

$$|\tau_m - \delta_{i_m}| = o(1)$$

- the most difficult part: show that

$$l_m = m$$

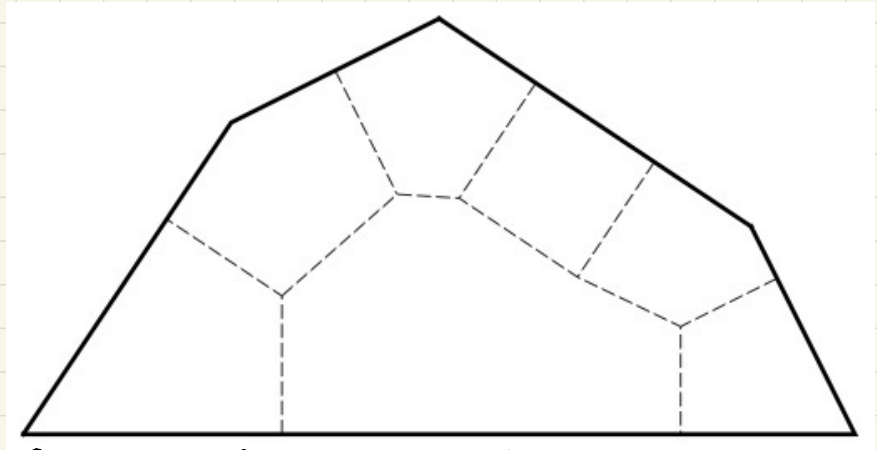
(in other words, we haven't missed any e.v.'s)

Done with the help of Dirichlet-Neumann bracketing:

- * add cuts with Dirichlet or Neumann (one by one)

- * compare with

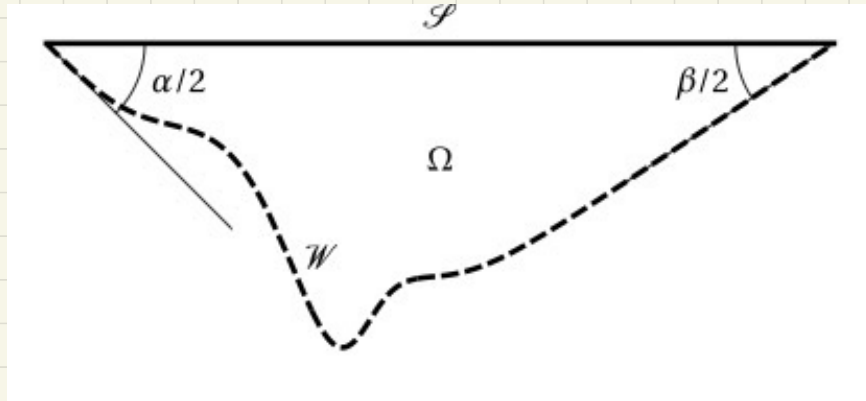
asymptotics of sloshing / other mixed Steklov-Dirichlet-Neumann problems + transplantation tricks



more
later

- account for curved boundaries **away** from the vertices (easy, there is a good **ansatz**.)
- account for curved boundary near the vertices (hard, potential theory in the **spirit of Costabel**)
- adjust for presence of exceptional angles

Asymptotics of eigenvalues of the sloshing and related problems



$$\mathcal{W} = \mathcal{W}_D \cup \mathcal{W}_N$$

$$\left\{ \begin{array}{l} \Delta U = 0 \quad \text{in } \Omega \\ U|_{\mathcal{W}_D} = 0 \quad \partial_n U|_{\mathcal{W}_N} = 0 \\ \partial_n U = \partial U \quad \text{on } \mathcal{S}^N \end{array} \right.$$

Done in the same manner as pure Steklov,
by matching solns of the sloping beach
problems near the corners

Thm [LPPS'21] For $0 < \frac{\alpha}{2}, \frac{\beta}{2} < \frac{\pi}{2}$

$$|S| \sigma_m = \pi \left(m - \frac{1}{2}\right) + \frac{\pi^2}{8} \left(\pm \frac{2}{\alpha} \pm \frac{2}{\beta}\right) + o(1),$$

$m \rightarrow \infty$

where $+$ is taken for the Dirichlet condition
near the corner and $-$ for Neumann

Remarks • Also works for $\frac{\alpha}{2}, \frac{\beta}{2} = \frac{\pi}{2}$ with some extra
geom conds

- If walls are straight near the corners, 0-term
is better
- Proves conj of Fox-Kuttler '1980s

Some open problems:

- Numerics suggest that our asymptotics "work" for angles $\in [\pi, 2\pi)$ for the Steklov, and $\frac{\alpha}{2}, \frac{\beta}{2} \in [\frac{\pi}{2}, \pi)$ for sloshing etc. We couldn't prove it as our remainder estimate for the sloping beach problem is not good enough.
- Numerics / hand-waving arguments also suggest that the next-order correction in the asymptotics for σ_m should come from the boundary curvature at the vertices

• What happens in 3D and higher? Only basics/specific examples are known so far:

* Steklov: [Ivrii 2019] + for cuboids [Girouard + Lagacé + Polterovich + Savo'19]

* sloshing in a particular prism [Mayrand + Séhécalt + St-Amant '21]

Remark. Recall that in the smooth case we had the uniform bound

$$|\sigma_{\Lambda, k} - \sqrt{\lambda_k(-\Delta_M) - \Lambda}| \leq C$$

for eigenvalues of \mathcal{D}_Λ . Is it possible to have a similar uniform bound for polygons, maybe with $-\Delta_M$ replaced by some other "boundary" operator (independent of Λ). The answer is **NO**, and it follows from Robin - DtN duality and results on asymptotics of $\sigma_{\Lambda, k}$ as $\Lambda \rightarrow -\infty$ for a fixed k derived from that and [Khalilé'18], [Khalilé/Pankrashkin'18], etc....

Part V.

Inverse Steklov problems

We start with a

Defn Two Riemannian manifolds with bdy, or two Euclidean domains are called **Steklov isospectral** if their Steklov spectra coincide

Two examples from [Girouard / Parnowski / Polterovich / Sher 14]

If M_1, M_2 are isospectral $(-\Delta)$ Riem. manifolds, then

$M_j \times (0, h)$ are Steklov isospectral

If g_1 and $g_2 = \rho g_1$ are two conf. equivalent metrics on Ω

with $\rho|_{\partial\Omega} = 1$, then (Ω, g_j) are Steklov isospectral

At the same time,

Open Question: do there exist non-isometric Steklov isospectral planar Euclidean domains?

Defn. We say that two domains Ω_I and Ω_{II} are asymptotically ^(Steklov) isospectral or quasi-isospectral if

$$|\sigma_k(\Omega_I) - \sigma_k(\Omega_{II})| = o(1) \quad k \rightarrow \infty$$

Fact Any two simply connected smooth planar domains with the same perimeter are asymptotically Steklov isospectral

Q: Which Steklov spectral invariants do we have, i.e. what geometric information can we recover from Steklov spectrum?

A. In the smooth case, the perimeter + in a non-simply connected case, the number of boundary components and their length [GPS'14]

We will now concentrate
on curvilinear polygons
only, a separate set of slides